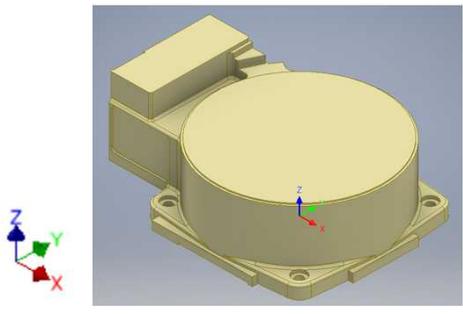
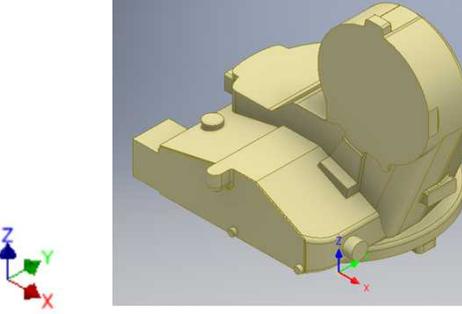
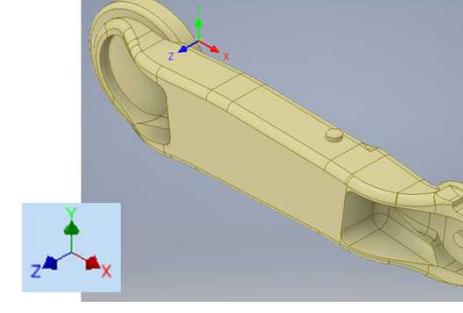
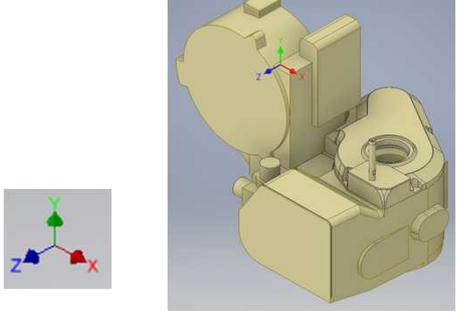
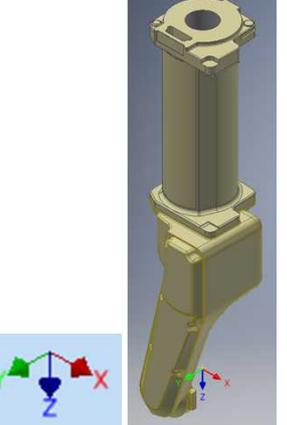
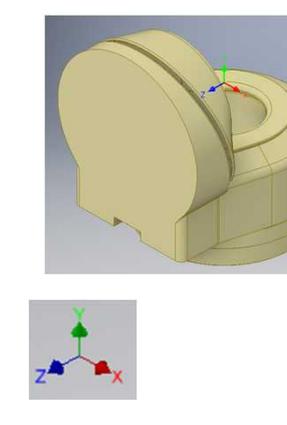
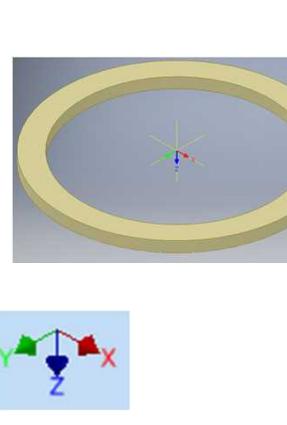


FD-B6L

<p>Base</p>  <p>原点：ロボット取付中心</p>	<p>Link1</p>  <p>原点：ロボット取付中心</p>	
<p>Link2</p>  <p>原点：ロボットセンタとJ2回転中心の交わる点</p>	<p>Link3</p>  <p>原点：ロボットセンタとJ3回転中心の交わる点</p>	
<p>Link4</p>  <p>原点：J4とJ5軸の交点</p>	<p>Link5</p>  <p>原点：J5とJ6軸の交点</p>	<p>Link6</p>  <p>原点：ツール取付面とJ6軸の交点</p>

